

Delay-line Anode for MCP-based Position Sensitive Detector at Rare RI Ring

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Rare RI Ring¹⁾ (R3) is a newly developed mass spectrometer for the measurement of exotic nuclei with a high precision of 10^{-6} . In order to achieve this goal, beam diagnostics need to be on the beam line (including BigRIPS, SHARAQ, and R3 injection)¹⁾ for several reasons: (1) velocity measurement with a precision of 10^{-4} is needed for mass determination;²⁾ (2) in order to improve the transport efficiency, emittance matching should be applied, which requires emittance measurement before the ring.^{3,4)} To achieve a precision of 10^{-4} for the velocity measurement, new position sensitive detectors with energy loss as low as 10^{-5} are needed, which cannot be achieved by conventional PPAC. High position resolution (< 1 mm) and high efficiency ($\sim 100\%$) are also needed. For these detectors, it is very important to use position sensitive anodes for collecting the secondary electrons. To achieve high position resolution, we chose 2D delay-line anode for Micro-Channel-Plate (MCP) based detectors. The result of the calibration and position resolution of the anode is shown in this report.

A mask with several holes (the size of the holes were 1 mm and 0.5 mm in diameter) was placed on the MCP, whose active area had a diameter of 120 mm, as illustrated in Fig. 1. We used the vacuum gauge as

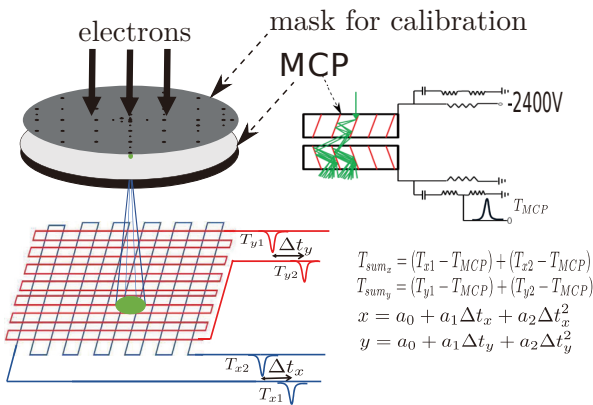


Fig. 1. Principle of the MCP with 2-D delay line anode; the MCP was placed in vacuum (3.5×10^{-3} Pa).

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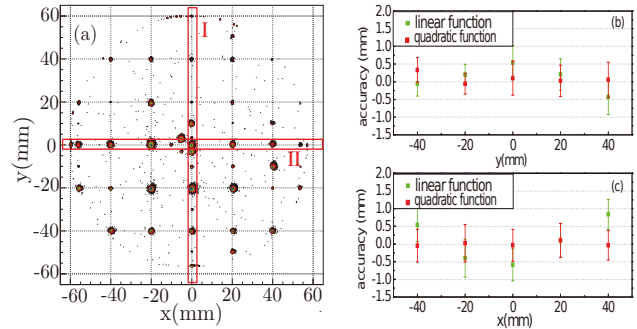


Fig. 2. (a) Image produced by the electrons that pass through the mask's holes and hit the MCP; (b), (c) Accuracy of the points in slice I and II in (a) by using linear and quadratic functions; the error bar represents the σ of the peak.

the source of electrons to calibrate the position of the anode. For each dimension of the delay-line anode, the sum of the times from the two ends, T_{sum} , should be constant, see Fig. 1. We chose 3σ of T_{sum} as a gate to cut the noise signal in both dimensions. The time information of each hole was obtained by projecting the points in the X axis and Y axis, and by fitting it using the Gauss function. It is not possible to use a linear function to calibrate the relationship between the time and position. Therefore, a quadratic function is chosen since it has a higher accuracy as shown in Fig. 2(b)(c). The position information of the holes after calibration is shown in Fig. 2(a). For holes with a diameter of 1 mm, the resolution in both the x and y directions is smaller than 0.6 mm in σ , which is required for high-resolution position sensitive detector.

An MCP with a delay-line anode that has a resolution smaller than 0.6 mm in σ is adequate for a position sensitive detector. One detector has already been developed and is under testing.⁵⁾ In the coming years, other position sensitive detectors with the same delay-line anode will be developed.

References

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